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Original Article

Improved methods for the analysis of circadian rhythms in correlated gene expression data

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Abstract

Circadian clocks regulate biological behaviours, such as sleeping and waking times, that recur naturally on an approximately 24-hour cycle. These clocks tend to be influenced by a variety of external factors, sometimes to the extent that it can have an impact on health. As an example in pharmacology, the effects of chemicals on the circadian rhythm in patients can be key to clarifying the relationship of drug efficacy and toxicity with dosing times. While pre-clinical experiments conducted to elucidate these effects may produce correlated data measured over time, such as gene expression profiles, existing methods for fitting parametric nonlinear regression models are, however, inadequate and can lead to unreliable, inconsistent parameter estimates and invalid inference. De-trending is widely used as a pre-processing step to address non-stationarity in the data, before fitting models based on the assumption of independence. However, as it is unclear that this approach properly accounts for the correlation structure, alternative methods that specifically model the correlation in the data based on conditional least squares and a two-stage estimation procedure are proposed and evaluated. A simulation study covering a wide range of scenarios and models shows that the proposed methods are more efficient and robust against model mis-specification than de-trending and, furthermore, they reduced estimation bias in the circadian period and provide more reliable confidence intervals.

Keywords: correlated gene expression data, de-trending method, nonlinear regression

1. Introduction

Most biological organisms, including humans, display an internal process (Erzberger *et al.*, 2013) that regulates their behaviour according to the time of day. The internal clocks that determine the natural recurrence of biological processes, such as sleep and wake times, on a twenty-fourhour cycle are called circadian clocks (Cammack *et al.*, 2006). In the study and development of drugs, circadian rhythms play a key role in understanding the relationship of efficacy and toxicity with dosing times (Paschos *et al.*, 2010). Experimental adjustments of administration times of drugs

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can minimize the toxicity and maximize the efficacy of drugs. In addition, the cited reference provides examples of how circadian rhythms may affect the treatment of hypertension and cancer.

A gene is said to be expressed when it produces a functional product, such as protein molecules, used in an organism's cells. Bioluminescence is used in quantifying the gene expression of a cell. To generate bioluminescence an oxidative enzyme, in the case of circadian rhythms luciferase (Allard & Kopish, 2008), is implanted in the membrane of a living cell to produce light. The light emission is based on the conversion of chemical energy to radiation and is very efficient in terms of the released heat, i.e., most of the chemical energy is converted to radiation. Produced light intensity from the cells is then measured, and is used as a response variable in relevant experiments (Albert *et al.*, 2008).

These technologies allow scientists to detect changes in the expression of genes over time. Responses arising from the study of circadian gene expression are measurements of intensity, in relative units, over a course of time.

The data used in this paper were produced in the pre-clinical investigation phase of drug development by a pharmaceutical company. Human cells in a well-plate were treated with a chemical compound and the gene expression profiles were recorded. The experiment was replicated four times and the gene expression level in each well was measured every 1.5 hours for 78 hours. The cells within each well were synchronized because the measured expression is population average for a well, and our goal was to inspect circadian rhythms. This experimental design gives serially correlated observations for each well. Of interest in this paper is the development of models that efficiently capture the oscillatory time-pattern of gene expression while accounting for the correlation. Of particular interest is estimation of the period, as this provides information about the effects of the chemical compound on the circadian rhythm.

Usually the response level in a circadian gene expression experiment decreases with time. To adjust the observations for this trend, a pre-processing step is proposed by Yang and Su (2010) to remove the linear trend by using simple regression, and then the de-trended data are modelled by ordinary least squares (OLS). De-trending is widely used to fit models for correlated gene expression data, and it is assumed to produce independent errors based on stationarity assumptions. In order to address non-stationary correlated responses, the de-trended responses are fit with sinusoidal models (Izumo et al., 2003, 2006; Kyriacou & Hall, 1980; Maier et al., 2009) assuming independent errors. However, it is unclear that this de-trending (DET) method is adequate to account for the potential correlations in the responses, and further, de-trending produces correlated residuals. Properly accounting for correlated responses is important, as failure to do so can lead to biased parameter estimates and underestimation of their standard errors (Bender & Heinemann, 1995).

Conditional least squares (Bates & Watts, 1988) and two-stage estimation approach (Seber & Wild, 2003) are alternative strategies for fitting regression models to correlated data. These two methods are not based on time series assumptions, but rather they intend to address the correlation problem by explicitly modelling the correlation structure. Both conditional least squares and two-stage estimation methods utilize least squares procedures, and therefore benefit from the standard distributional properties of least squares estimators. They also tend to be computationally tractable. Neither method has previously been proposed in the literature for modelling circadian rhythms in correlated gene expression data.

This paper evaluates the conditional least squares and the two-stage estimation methods in nonlinear regression modelling of correlated gene expression data displaying an oscillatory pattern. The focus is on efficiency and reliability of these methods in estimating the oscillation period. The use of nonlinear models is novel to this application area. By directly modelling the trend and correlation pattern in the data, the limitations of the de-trending approach described above can be avoided. Comparisons of the proposed methods with the de-trending approach over a range of scenarios and models, including situations where the fitted model is incorrectly specified, are provided based on simulations.

2. Methods

Consider the nonlinear regression model of the relationship between an independent variable t and a dependent response variable y measured at n time points for each of r individuals,

$$\mathbf{y}_i = \mathbf{f}(\mathbf{t}_i; \boldsymbol{\theta}) + \mathbf{\varepsilon}_i; \ i = 1, \dots, r,$$
(1)

where $\mathbf{y}_i = (y_{i,1}, \dots, y_{i,n})'$ is the observed response vector for the *i*th individual, $\mathbf{t}_i = (t_{i,1}, \dots, t_{i,n})'$ is a time vector, $\mathbf{f}(\boldsymbol{\theta}) = (f(t_{i,1}; \boldsymbol{\theta}), \dots, f(t_{i,n}; \boldsymbol{\theta}))'$ for some nonlinear function f of t with an unknown parameter vector $\boldsymbol{\theta}$ and $\boldsymbol{\varepsilon}_i = (\varepsilon_{i,1}, \dots, \varepsilon_{i,n})'$ is an error vector. Assuming the repeated measures on each individual follow a stationary autoregressive process of order 1, AR(1), the error components then are linearly related between time points j and j-1

$$\varepsilon_{i,j} = \rho \varepsilon_{i,j-1} + \delta_{i,j}; \quad j = 1, \dots, n,$$
⁽²⁾

where $|\rho| < 1$ is the correlation between $\mathcal{E}_{i,j-1}$ and $\mathcal{E}_{i,j}$, and $\delta_{i,j}$ are assumed to be normal, independent and identically distributed with zero mean and common variance σ^2 .

Two possible ways to fit an AR(1) model when no assumptions are made on the joint distribution of the error terms are conditional least squares and the two-stage estimation method. Both methods, which are described below, fit the nonlinear regression model by least squares.

2.1 Conditional least squares estimation

The least squares estimation method is adapted to correlated responses by replacing the expected response from the model by a conditional expectation in the sum of squared deviations (Klimko & Nelson, 1978). In the case of correlated errors coming from a stationary AR(1) process in Equation (2) the conditional least squares (CLS) model can be shown to obey

$$y_{i,j} - f(t_{i,j}; \boldsymbol{\theta}) = \rho(y_{i,j-1} - f(t_{i,j-1}; \boldsymbol{\theta})) + \delta_{i,j}; \ j = 2,...,n, \ (3)$$
$$y_{i,j} = \rho y_{i,j-1} + f(t_{i,j}; \boldsymbol{\theta}) - \rho f(t_{i,j-1}; \boldsymbol{\theta}).$$

As normally distributed errors in an autoregressive model makes maximum likelihood equivalent to least squares estimation, the CLS method produces parameter estimates with similar properties as maximum likelihood estimators. In particular, the estimates obtained are consistent and asymptotically normal under mild regularity conditions (Klimko & Nelson, 1978). Note that the degrees of freedom for this model (3) are reduced by the first order autoregressive process, which impacts precision of the estimates. In addition, the increased number of model parameters increases the risk of convergence problems in iterative fitting. 694

2.2 Two-stage estimation

A two-stage (TS) approach that consists of two ordinary least squares (OLS) procedures, for estimating the parameters in nonlinear time series regression with autoregressive errors, has been proposed (Gallant & Goebel, 1976). Applied to the problem considered here, first the correlation structure is ignored and the model (1) is fitted by OLS to produce estimates $\hat{\boldsymbol{\theta}}_{\text{OLS}}$ of $\boldsymbol{\theta}$ and fitted values $f(t_{i,j}; \hat{\boldsymbol{\theta}}_{\text{OLS}})$. The residual vector for the *i*th individual,

$$\hat{\boldsymbol{\varepsilon}}_i = \mathbf{y}_i - \mathbf{f}(\mathbf{t}_i; \hat{\boldsymbol{\theta}}_{OLS}),$$

is used to produce an estimate of ρ (Park & Mitchell, 1980) given by

$$\hat{\rho}_i = \frac{\displaystyle\sum_{j=2}^n \hat{\varepsilon}_{i,j} \hat{\varepsilon}_{i,j-1}}{\displaystyle\sum_{j=2}^{n-1} \hat{\varepsilon}_{i,j}^2}.$$

In the second stage, by using the mean of $\hat{\rho}_1, \dots, \hat{\rho}_r$, denoted $\hat{\rho}$, to estimate the common correlation ρ , a modified model (4)

$$z_{i,j} = g(t_{i,j}; \boldsymbol{\theta}) + \delta_{i,j}; \ i = 1, \dots, r,$$

$$\tag{4}$$

where

$$z_{i,j} = \begin{cases} (1 - \hat{\rho}^2)^{\frac{1}{2}} y_{i,j} & ; j = 1 \\ y_{i,j} - \hat{\rho} y_{i,j-1} & ; j = 2, \dots, n, \end{cases}$$

and

$$g(t_{i,j}; \boldsymbol{\theta}) = \begin{cases} (1 - \hat{\rho}^2)^{\frac{1}{2}} f(t_{i,j}; \boldsymbol{\theta}) & ; j = 1 \\ f(t_{i,j}; \boldsymbol{\theta}) - \hat{\rho} f(t_{i,j-1}; \boldsymbol{\theta}) & ; j = 2, ..., n, \end{cases}$$

is constructed and fitted using OLS.

The TS procedure produces estimators with asymptotic properties similar to OLS estimators (Gallant & Goebel, 1976) and, unlike in CLS, no observations are excluded from the analysis.

2.3 Nonlinear functions

Although several functions can be found in the literature to model data displaying a sinusoidal pattern with a decreasing trend over time, in this paper the following three functions are considered as they display patterns consistent with real gene expression data. The one-sine function is a modified version of Izumo *et al.* (2003) with added decreasing trend

$$f(t_{i,j};\boldsymbol{\theta}) = \alpha + \beta t_{i,j} + a \exp(-dt_{i,j}) \sin(\frac{2\pi t_{i,j}}{\tau} + \Phi),$$

where τ is the period, a is the amplitude, Φ represents the phase of the sine wave, d is a damping parameter, α is an intercept and β is a slope of the linear trend. The song-sine function modified from Kyriacou and Hall (1980) extends the one-sine function to allow a linear constant displacement a_s in the amplitude, and is given by

$$f(t_{i,j};\boldsymbol{\theta}) = \alpha + \beta t_{i,j} + (a_s + a \exp(-dt_{i,j})) \sin(\frac{2\pi t_{i,j}}{\tau} + \Phi).$$

Finally, in order to deal with the potential of more than one sinusoidal pattern, the two-sine with damping function

$$f(t_{i,j}; \boldsymbol{\theta}) = \alpha + \beta t_{i,j} + a \exp(-dt_{i,j}) \sin(\frac{2\pi t_{i,j}}{\tau} + \Phi) + b \sin(\frac{2\pi t_{i,j}}{\upsilon} + \Phi),$$

where b and v are the amplitude and the period of the second sine term, respectively, is proposed as a novel function. Note that the possibility of more than one sine pattern has arisen in discussions with subject matter specialists.

3. Simulation Study

A simulation study was carried out to assess the methods in a variety of scenarios, including cases where the fitted model is incorrectly specified. In order to mimic the correlations in circadian gene expression over time, datasets were simulated with various levels of correlation ρ in the AR(1) process. In particular, the *i*th dataset (i = 1, ..., r) of size-*n* sample is generated from

$$y_{i,j} = \begin{cases} f(t_{i,j}; \theta) + \delta_{i,j} & ; j = 1\\ \rho y_{i,j-1} + f(t_{i,j}; \theta) - \rho f(t_{i,j-1}; \theta) + \delta_{i,j} & ; j = 2,...,n, \end{cases}$$

where $\delta_{i,j}$ are independent and identically distributed $N(0,\sigma^2)$.

Results presented in this paper are for simulated datasets generated under the parameter values $\boldsymbol{\theta}$ shown in Table 1. In addition, the AR (1) parameters are $\rho = (0, 0.25, 0.75)$ and $\sigma^2 = 25$. For each study, repeated measures are simulated for r = 4 independent individuals at times $t_{i,j} = 0, 1.5, \dots, 78$, so that n = 53. The parameter values were selected so that the simulated datasets resemble observed circadian expression data.

For instance, the value $\tau = 24$ is in the range of circadian period length (20-28h) determined by Yang and Su (2010). Shown in Figure 1 are examples of synthetic datasets generated by the three models in the previous section.

For each simulation run, a total of 10,000 replicate studies are generated and analysed using R (R Core Team, 2013) with the nls function based on Gauss-Newton algorithm; see Ritz and Streibig (2008) and Crawley (2013) for

N 11					θ				
Model	τ	υ	a_{s}	а	b	Φ	d	α	β
one-sine	24	-	-	180	-	0.31	0.07	330	-3
song-sine two-sine with damping	24 24	- 35	0.5	180 180	- 0.5	0.31 0.31	$\begin{array}{c} 0.07 \\ 0.07 \end{array}$	330 330	-3 -3

Table 1. The three sets of parameter values used in the simulations.

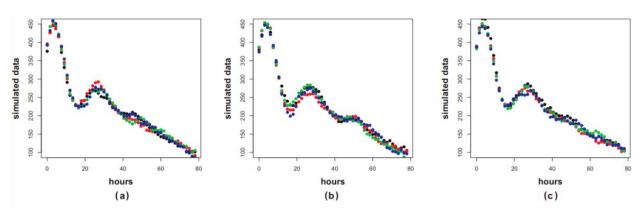


Figure 1. Example of the synthetic time-series datasets generated by the following functions: (a) one-sine, (b) song-sine and (c) two-sine with damping with AR(1) errors at $\rho = 0.75$ and $\sigma^2 = 25$.

details. In order to assess the efficacy of each method, parameter estimates were investigated and compared in terms of bias, relative difference between the standard deviation of estimates from replicate studies and the mean of standard errors produced by non-linear least squares fitting, root mean square errors, and coverage probability.

The main parameter of interest to identify from circadian rhythm data is the period τ , since it is used to predict the body's response to treatment and in the design of proper protocols for drug administration. Let $\hat{\tau}_m$ denote the period estimate from the *m*th simulation run, and let $\hat{\tau}$ be the average of $\hat{\tau}_m; m = 1, 2, ..., M$. The bias of the estimator is defined as

$$\% \operatorname{Bias} = 100 \left(\frac{\operatorname{mean}(\hat{\tau}) - \tau}{\tau} \right)$$
$$= 100 \left(\frac{\operatorname{Bias}(\hat{\tau})}{\tau} \right).$$

Similarly, to assess the bias in variance estimates, the relative difference between the standard deviation and the standard error for the estimate is given by

% Diff =
$$100 \left(\frac{\text{SD}(\hat{\tau}) - \text{SE}(\hat{\tau})}{\text{SE}(\hat{\tau})} \right)$$
,
where $\text{SD}(\hat{\tau}) = \sqrt{\frac{1}{M-1} \sum_{m=1}^{M} (\hat{\tau}_m - \text{mean}(\hat{\tau}))^2}$ and

 $SE(\hat{\tau}) = \frac{1}{M} \sum_{m=1}^{M} SE(\hat{\tau}_m)$, with $SE(\hat{\tau}_m)$ the standard error of the period estimate for the *m*th simulated dataset.

Efficiency of the method is measured by the root mean square error

$$RMSE = \sqrt{\left(SD(\hat{\tau})\right)^2 + \left(Bias(\hat{\tau})\right)^2}$$

Finally, the estimate and the standard error are combined to construct the $100(1-\alpha)\%$ confidence interval (CI) for τ given by

$$\hat{\tau}_m - t_{\frac{\alpha}{2}, \nu} SE(\hat{\tau}_m) \le \tau \le \hat{\tau}_m + t_{\frac{\alpha}{2}, \nu} SE(\hat{\tau}_m),$$

where $t_{\frac{\alpha}{2}, \nu}$ is the upper $\frac{\alpha}{2}$ quantile of student *t* distribution

with v degrees of freedom. How often the confidence interval covers the true value of τ provides an estimate of the coverage probability for τ and hence a measure of statistical inference validity.

Note that the Gauss-Newton algorithm does not necessarily convergence in all instances, so M is the total number of successful fits with converged parameters, and this differs between the different methods.

4. Results

This section presents simulation results from conditional least squares and two-stage methods in fitting the models described in Section 2.3. Also presented for comparison are the results from de-trending. Evaluations are presented both with the same type of model generating the data and fit to the data, as well as for cases with incorrectly specified fitted model. The latter cases reflect real-life conditions, where the data generating model is unknown, and help critically evaluate the robustness of the methods against model mis-specification. Table 2 summarizes the performance in terms of bias (%Bias), relative difference (%Diff) and root mean square error (RMSE) for the methods, with the data generated by the one-sine model. The results show that for the correct model type at all ρ (0.00, 0.25 and 0.75), estimates from DET are negatively biased. Moreover, DET overestimates the variance of $\hat{\tau}$ and is consequently less efficient in terms of the RMSE. This leads to poor coverage probability, as shown in Figure 2 (a). On the other hand, CLS and TS produce unbiased estimates and good variance estimates. Consequently, their coverage probabilities are close to the expected value.

Table 2. Percentage bias, percentage relative difference and root mean square error of the period estimate $\hat{\tau}$ for DET, CLS and TS procedures when the true model is one-sine with $\tau = 24$.

Eitte dame del		ρ		DET			CLS			TS	
Fitted model		P	%Bias	%Diff	RMSE	%Bias	%Diff	RMSE	%Bias	%Diff	RMSE
	_	0.00	-1.3481	-57.8739	0.3460	0.0001	1.3136	0.1352	-0.0010	2.8511	0.1107
one-sine	τ	0.25 0.75	-1.3402 -1.3114	-47.9025 -14.6151	0.3558 0.4097	0.0057 0.0239	2.1349 4.9797	0.1857 0.4021	0.0034 0.0242	4.3817 8.1855	0.1354 0.2287
		0.00	-0.7153	-43.1825	0.2461	0.0006	1.9455	0.1366	0.0001	3.5042	0.1116
song-sine	τ	0.25 0.75	-0.6866 -0.2137	-24.5922 104.4706	0.2866 0.6605	0.0037 0.0341	3.5934 10.9491	0.1888 0.4228	0.0027 0.0266	5.5995 11.2017	0.1367 0.2332
	τ	0.73 0.00 0.25	-0.2137 -1.0407 -0.9155	39.7004 74.0320	0.4935 0.5802	-0.0189 -0.0037	4.4714 5.5841	0.4228 0.1463 0.2015	-0.0398 -0.0537	6.8993 9.1860	0.1229 0.1516
two-sine with		0.75	-0.8384	96.0890	0.6624	0.1654	8.6487	0.4588	-0.0250	15.0083	0.2635
damping	υ	0.00 0.25 0.75	-163.4983 -159.3910 -142.6832	8013.8058 8328.1164 8043.6805	67.9124 67.4969 60.0745	34.7031 33.7229 34.2731	233.4452 360.1641 262.5797	24.0473 31.1765 30.4309	36.4217 35.3224 31.1163	279.8772 290.9461 383.1758	23.5832 24.7837 33.7434

Note: The period estimates for τ and ν when the fitted model is two-sine with damping.

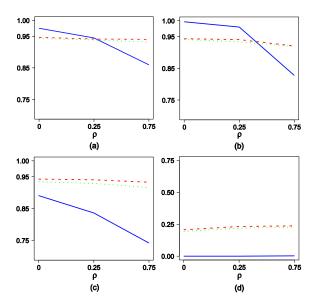


Figure 2. Plots of coverage probability of 95% confidence interval for the period τ using DET (solid line), CLS (dashed line) and TS (dotted line) when the true model is one-sine and the fitted model is (a) one-sine, (b) song-sine and (c) two-sine with damping. Coverage probability plots for \mathcal{V} in the two-sine with damping model are shown in (d).

For cases where the fitted model was mis-specified, when the simple song-sine function was used to fit the data, DET produced estimates that are less biased than when the correct model is fitted. However, the results also suggest that standard errors of parameter estimates are overestimated for low and moderate correlations and underestimated for strong correlations. This leads to overall poor coverage of the confidence intervals, as shown in Figure 2 (b). When the fitted model is two-sine with damping, both $\hat{\tau}$ and the standard error of $\hat{\tau}$ are underestimated by the DET method. On the other hand, both CLS and TS produced unbiased estimates in all cases but they tend to slightly underestimate the variances, especially when the data are strongly correlated, see Table 2. Also, as Figures 2 (a, b and c) show, CLS and TS procedures produce confidence intervals that are reasonably consistent with the theoretical expectations, albeit with slightly decreasing coverage as correlation increases.

All the methods perform poorly in estimation of the second period term \mathcal{U} when the fitted model is twosine with damping. DET severely underestimates, whereas CLS and TS consistently overestimate \mathcal{U} , and all these methods underestimate the standard error. Not surprisingly, this estimation bias leads to the poor coverage probabilities shown in Figure 2 (d).

Following conclusions when the true models are song-sine and two-sine with damping can be drawn from Figures 3-4 and Tables 3-4. In the simulations with data generated under the song-sine model, results in Figure 3 and Table 3 show that DET again performs quite poorly, whether or not the fitted model is correctly specified. On the other hand, the findings for CLS and TS are consistent with the earlier results in Figure 2 and Table 2.

Table 4 shows simulation the results when the true model has an extra sine term with as second period ($\tau = 24$ and $\upsilon = 35$). The results again show that even though the fitted model was correctly specified, DET consistently underestimated both periods and produced variance estimates that are too small. In contrast, by explicitly modelling correlation in the data, the proposed CLS and TS methods perform far better in all cases. Moreover the coverage probabilities under CLS are close to 0.95 but, as TS produces slight underestimates of variances (as given by %Diff), its coverage probability shown in Figure 4 is slightly less than expected.

In summary, CLS and TS give more efficient estimates and are comparatively robust against model misspecification. This reduces bias in estimates of the circadian period and gives better coverage probabilities. On the other hand, by not properly accounting for the correlation, DET has biases in estimates of period and standard error.

5. Example

To compare the DET method with the proposed CLS and TS methods in real-life situations, all three methods, were applied to data that, as explained in the introduction, comes from experiments run over 78 hours with a drug treat-

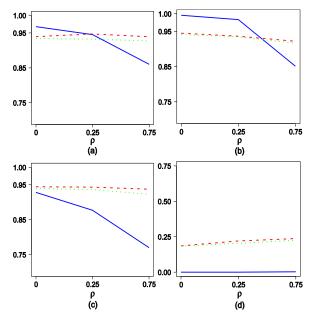


Figure 3. Plots of coverage probability of 95% confidence interval for the period τ using DET (solid line), CLS (dashed line) and TS (dotted line) when the true model is songsine and the fitted model is (a) one-sine, (b) song-sine and (c) two-sine with damping. Coverage probability plots for \mathcal{D} in the two-sine with damping model are shown in (d).

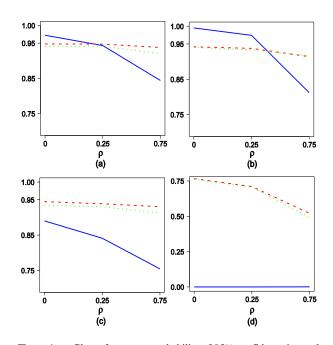


Figure 4. Plots of coverage probability of 95% confidence interval for the period τ using DET (solid line), CLS (dashed line) and TS (dotted line) when the true model is two-sine with damping and the fitted model is (a) one-sine, (b) song-sine and (c) two-sine with damping. Coverage probability plots for \mathcal{U} in the two-sine with damping model are shown in (d).

Table 3.	Percentage bias, percentage relative difference and root mean square error of the period estimate $ au$ for DET, CLS and TS
	procedures when the true model is song-sine with $\tau = 24$.

Eitte dasse de	.1	ρ		DET			CLS			TS	
Fitted mode	21	Ρ	%Bias	%Diff	RMSE	%Bias	%Diff	RMSE	%Bias	%Diff	RMSE
one-sine	τ	0.00 0.25 0.75	-1.2403 -1.2461 -1.2326	-58.5760 -48.5675 -14.8026	0.3205 0.3336 0.3923	0.0564 0.0545 0.0738	0.4097 1.2011 3.6574	0.1325 0.1812 0.3897	0.0364 0.0299 0.0291	2.4322 4.5569 8.7886	0.1089 0.1337 0.2266
song-sine	τ	0.00 0.25 0.75	-0.7335 -0.7045 -0.3208	-46.3534 -30.2979 87.5651	0.2399 0.2714 0.5989	-0.0007 0.0034 0.0270	1.8875 3.6546 10.3293	0.1328 0.1833 0.4068	-0.0009 0.0019 0.0259	3.5155 5.6232 11.1047	0.1091 0.1338 0.2282
two-sine with	τ	0.00 0.25 0.75	-1.1211 -0.9925 -0.8836	5.3314 47.9338 84.2489	0.4112 0.5033 0.6193	0.0470 0.0857 0.2289	2.4027 3.6965 7.4677	0.1397 0.1940 0.4459	-0.0049 -0.0143 0.0087	4.3776 7.0522 14.0669	0.1163 0.1449 0.2570
damping	υ	0.00 0.25 0.75	-153.3599 -146.9491 -133.8591	7803.6494 7327.3300 7826.7206	62.4126 55.6965 55.8487	39.6778 33.7229 38.7591	262.1625 360.1641 269.6656	26.2878 31.1765 31.7897	38.5423 35.3224 36.5362	239.0626 269.1014 337.7400	24.4712 27.2147 36.2693

Note: The period estimates for τ and ν when the fitted model is two-sine with damping.

Table 4. Percentage bias, percentage relative difference and root mean square error of the period estimate $\hat{\tau}$ for DET, CLS and TS procedures when the true model is two-sine with damping with $\tau = 24$ and $\upsilon = 35$.

Fitted mode	1	ρ		DET			CLS			TS	
	51	Ρ	%Bias	%Diff	RMSE	%Bias	%Diff	RMSE	%Bias	%Diff	RMSE
one-sine	τ	0.00 0.25 0.75	-1.2168 -1.2087 -1.1777	-57.5719 -47.5178 -13.8429	0.3177 0.3290 0.3895	0.2142 0.2221 0.2546	2.1370 3.2454 6.6532	0.1468 0.1969 0.4170	0.2055 0.2073 0.2190	3.3333 4.8921 8.7644	0.1224 0.1457 0.2371
song-sine	τ	0.00 0.25 0.75	-0.8361 -0.7988 -0.2610	-43.8445 -21.9388 116.3003	0.2661 0.3098 0.7000	-0.0169 -0.0404 -0.0677	2.3665 4.4336 12.716	0.1381 0.1914 0.4310	0.0535 0.0698 0.1225	3.7040 6.0290 12.5079	0.1133 0.1391 0.2389
two-sine with	τ	0.00 0.25 0.75	-1.2081 -1.0585 -1.0024	30.1877 64.8227 83.7758	0.4925 0.5701 0.6399	-0.0282 0.0016 0.1259	2.3439 5.1759 9.1935	0.1410 0.1979 0.4581	-0.0467 -0.0395 0.0296	4.1905 7.8307 15.9557	0.1185 0.1483 0.2655
damping	υ	0.00 0.25 0.75	-135.2289 -132.2588 -123.5109	8163.4433 8097.1445 8008.4038	74.4227 70.3876 65.1504	-3.1040 -5.3984 -6.7022	245.8983 255.0431 258.6963	17.2457 23.2962 29.4377	-2.5064 -4.0577 -10.5172	188.3904 245.8808 422.4302	15.7257 20.4272 36.1448

Note: The period estimates for τ and D when the fitted model is two-sine with damping.

ment. As mentioned before, the same treatment was applied to four sets of cells, each measured every 1.5 hours. The intensity of bioluminescence was measured as indicator of a gene's expression level. In the data analysis, only those responses that showed an effect at 0h were included. A scatter plot of the data displays cyclic patterns with a linear decreasing trend over time, as seen in Figure 5. The sinusoidal functions described in Section 2 with autoregressive errors of order 1, AR (1), were tested for modelling these data.

In order to compare the performances of DET with the proposed methods, CLS and TS, Table 5 summarizes the analyses in terms of the 95% confidence interval (CI) for τ , and the residual standard errors $\hat{\sigma}$ from DET, CLS and TS approaches. Table 6 shows the lack of fit tests comparing residuals from the nonlinear models to residuals for one-way ANOVA models of the replicate observations at each time point that account for the correlation structure. Plots of the fitted models are given in Figure 6.

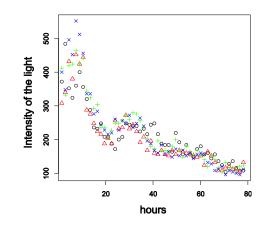


Figure 5. Circadian gene expression over time as measured by intensity of light, in relative units. The four replicates at each time point are shown with different symbols.

Table 5. Estimates and CI's of the circadian period in a real gene expression dataset obtained using three different models fitted by DET, CLS and TS procedures.

E44 d d.1		DET	,	CLS		TS	
Fitted model		95% CI	$\hat{\sigma}$	95% CI	$\hat{\sigma}$	95% CI	$\hat{\sigma}$
one-sine	τ	24.74 ± 1.14	33.37	24.15 ± 1.89	26.39	26.50 ± 1.63	27.74
song-sine	τ	25.88 ± 1.10	32.99	23.97 ± 1.45	26.35	26.89 ± 1.73	27.73
two-sine with	τ	24.75 ± 1.15	33.43	24.89 ± 2.48	26.45	26.45 ± 1.46	27.44
damping	υ	-6.15 ± 0.23		29.38 ± 3.76		55.16 ± 8.54	

Table 6. Lack of fit test for one-sine, song-sine and two-sine with damping models fitted by DET, CLS and TS.

Fitted model	E	ЭЕТ	CI	LS	TS		
Fitted model	F	<i>p</i> -value	F	<i>p</i> -value	F	<i>p</i> -value	
one-sine	2.561	8.703E-06	1.425	0.062	1.334	0.099	
song-sine	2.451	2.467E-05	1.416	0.067	1.353	0.090	
two-sine with damping	2.638	6.011E-06	1.464	0.052	1.141	0.274	

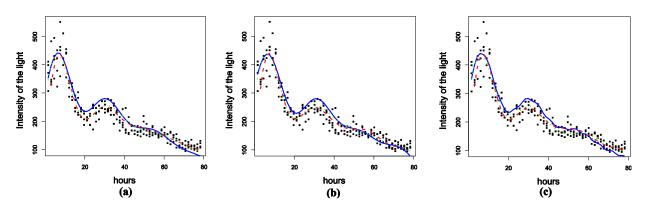


Figure 6. Fitted models (a) one-sine, (b) song-sine and (c) two-sine with damping to gene expression observations using DET (solid line), CLS (dashed line) and TS (dotted line) procedures.

The results show that for all the fitted models, the CLS estimates of the circadian periods are approximately 24 h with standard errors that are smaller than those obtained using DET and TS. The TS approach produces period estimates that are approximately 26 h with moderate residual errors. In contrast, the DET method produces period estimates around 25 h with the largest residual standard errors.

The lack of fit tests show that the CLS and TS methods provide good fits to the data, since there is no evidence of lack of fit. However DET fit the data poorly, as presented in Table 6. This is substantiated by plots of the fitted models, showing that the proposed methods produced the best fit to the observed cyclic pattern, as shown in Figure 6.

6. Conclusions

In this paper, we compared de-trending (DET) as the current baseline method for analyzing circadian rhythms in gene expression profiles to conditional least squares (CLS) and two-stage (TS) estimation as alternative methods. Simulation results clearly suggest that DET produced biased estimates of the circadian period and poor variance estimates, leading to invalid statistical inference. On the other hand, the proposed methods are not only much more efficient and robust against model mis-specification, but also had reduced bias in estimates of the circadian period and more reliable confidence intervals. The TS method produced slightly poorer confidence intervals than CLS in cases with high correlation, due to underestimated standard errors of parameter estimates. Although both proposed alternative methods provided good fits to real data, CLS produced more valid confidence intervals. In further work, we will propose methods for comparatively accurate variance estimation by maximum likelyhood, and will explore more sophisticated models capable of capturing complex data patterns.

The work here clearly illustrates de-trending to address non-stationarity of correlated data, although commonly used, should be undertaken with caution. In contrast, methods that explicitly account for the correlation, such as conditional least squares and two-stage estimation of nonlinear regression models, are viable and potentially more reliable and robust against model mis-specification. Finally, approaches such as CLS and TS are relatively straightforward to implement using standard statistical software packages, and their usage, for example in human drug development studies to understand circadian rhythms interfering with drug metabolism, should be encouraged.

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